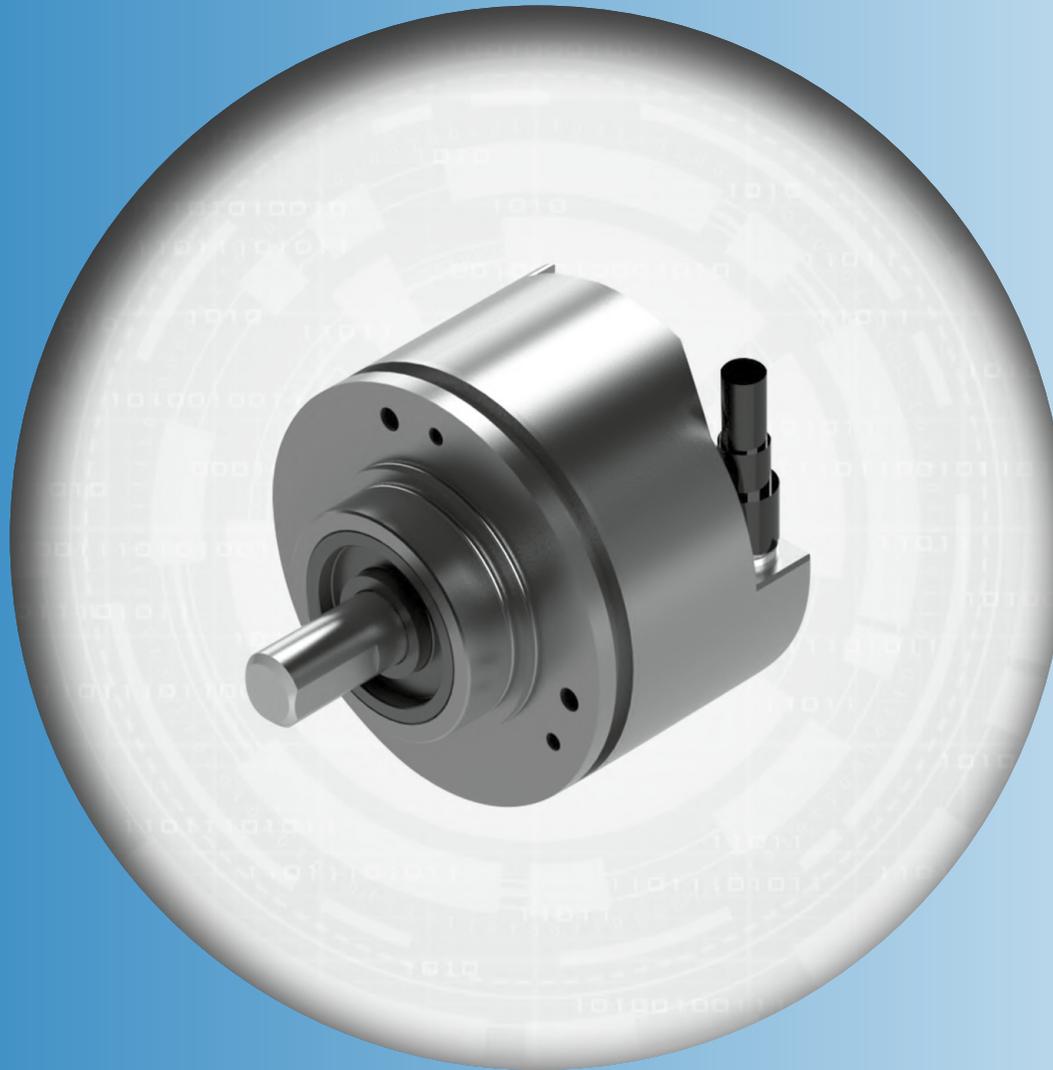


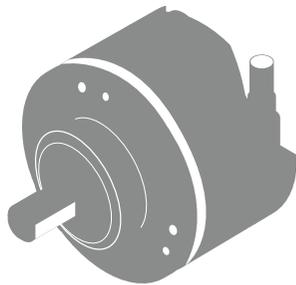
# **hohner**

Elektrotechnik Werne



**ENCODER  
INCREMENTAL  
PROGRAMMABLE  
SERIE PR90**

Your partner for standard and special designs  
– accurate, reliable and quick –



## PR90 / PR90H

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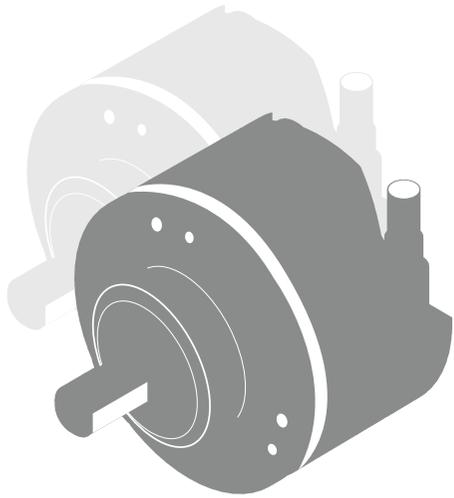
## CONNECT

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# PR90 / PR90H



## Features



USB and graphical interface programming options for the PR90 programmable incremental optical encoder:

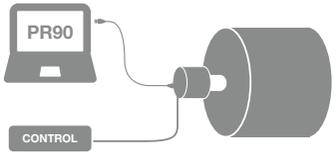
- ..... Incremental optical encoder, programmable for any possible number of pulses from 1 to 65.536 pulses per rotation.
- ..... Output Level selectable - HTL ( Push-Pull ) / TTL (RS422) regardless of input voltage.
- ..... Reference signal width (Z) - 90° or 180°
- ..... Reference signal positioning (Z) electrical vs. mechanical – 0° to 360°
- ..... Selectable rotation direction:  
CW (as seen from the axis, clockwise rotation)  
CCW (as seen from the axis, counter-clockwise rotation)
- ..... Independent channel by channel inversion option.  
Very useful in case of connection errors.
- ..... Remote maintenance and programming options.



Direct USB2 to USB2 encoder connection to any computer or Tablet-PC running Windows, MAC OS or Linux, without the need for intermediate adapter boxes.

..... **Power-On programming**  
*(encoder powered up)*

Encoder can be programmed while it is powered up, with no need to disconnect it from the machine.



..... **Power-Off programming**  
*(without powering up the encoder)*

Ability to program the encoder without the need for it to be powered up, only by connecting the encoder to the PC programmer.





## Auto sensing features

- ..... **Automatic voltage detection.** The equipment determines the output level (HTL/TTL) according to input voltage. From 4.5Vdc to 10Vdc output will remain in TTL, from 11Vdc to 30Vdc output level will be maintained in HTL as long as the device is programmed for HTL output.
- ..... **Automatic overload detection in the encoder driver.** In the event of a short circuit or overload in any of the outputs, the device will switch to TTL until the error is remedied. The encoder's LED will blink red and the graphic interface will display the relevant red indicator, registering the error, without interrupting the normal function of the device.
- ..... **Automatic Driver/PLC input impedance detection.** When the encoder is programmed for HTL outputs, if a driver/PLC with TTL inputs (1200 x Channel) is connected, the encoder will switch outputs to TTL automatically.
- ..... **Automatic humidity detection inside the encoder.** Water, humidity and condensation alarms. The encoder's LED will blink red and the graphic interface will display the relevant red indicator, registering the error, without interrupting the normal function of the device.
- ..... **Optical error detection.** Any dysfunction in the OptoAsic illumination or breakage of any of the optical elements is automatically detected and is described by the graphical interface alarms, logging the error, without interrupting the normal operation of the encoder.

## Working margins

The PR90 is ready to work from 4.5 Vdc to 30 Vdc, with HTL and TTL loads

Operating temperature range from -20°C to +85°C

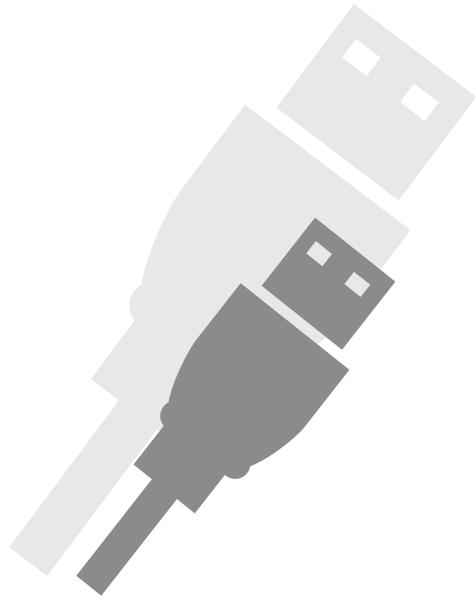
Protection IP65

Humidity levels should not surpass 98% without condensation



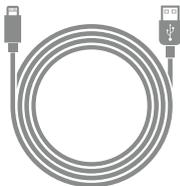
## Protection

- **Over voltage and power supply inversion protection.** The encoder is protected to prevent its destruction in case of reverse polarity of power and/or spikes exceeding 35Vdc.
- **Voltage drops.** The device stops working below 3.9 Vdc. Up to this point the PR90 maintains the outputs at standard TTL levels, and if the voltage drop has been excessively slow the encoder goes into protection mode; to reset the rated voltage to recover its normal operation you must just turn it off and on again.
- **Electrostatic and/or electromagnetic discharges.** Complies with the EMC directive (UNE-EN 61000-6-2:2006 + ERR:2009 and UNE-EN 61000-6-3:2007 + A1:2012). Although the equipment is protected to withstand electrostatic discharge above  $\pm 15\text{KVolt.}$ , occasionally the signal may lose a certain number of pulses during the discharge, at this point the equipment will reset the signal in under 100msec, the standard delay for a Watch-Dog circuit.
- **Active reset of the high-efficiency uController.** This circuit resets uController operation in extreme cases of malfunction. For example, this situation can occur in unstable or high-noise power connections.
- **False power connections.** The encoder is protected to withstand being switched on and off repeatedly within the margins of usual operation, without the equipment being harmed.  
 *It is not recommendable, like with any other electrical device, to turn the equipment on and off repeatedly in rapid succession while connected to mains power.*
- The electronic circuit has **ultra-fast electronic fuses**; in the event of a fault or failure, these fuses avoid greater damage and more expensive repairs.
- Electronics designed under the **BSI security regulations**, so as to avoid smoke and fire.
- **4-layer printed circuit** designed under MIL standards, to offer greater mechanical robustness in order to avoid external radio-magnetic influences.



**connect**

## Requirements



uUSB/USB cable



PC or Tablet-PC running on Windows, Mac OS or Linux



Download the programming software from the Hohner Automation website

**Minimum system requirements for the programming computer**

Recommended OSs: Windows 7, OS 6 o higher.  
Processor Intel I3 or similar with 2Gb RAM. Free USB1 or USB2 port.  
Internet connection. Virus and trojan free.

For the PR90 programmable incremental optical encoder to work correctly, you must follow the detailed configuration instructions below:

## Step 1: Connect the PR90 encoder to a USB port

1.1 ... **direct connection to a USB port**

You must open the connection cover located at the back of the PR90 encoder.  
The connection is direct, using a uUSB / USB cable to connect to any computer or tablet-PC, without any other equipment being required.



## Step 2: Programming software installation

2.1 ... **download the programming software**

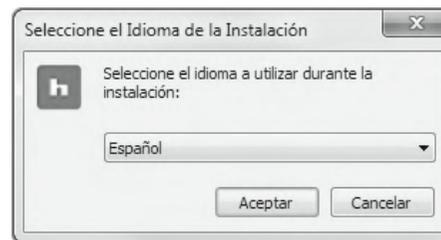
From the Hohner website, download the programming software required for your Operating System.

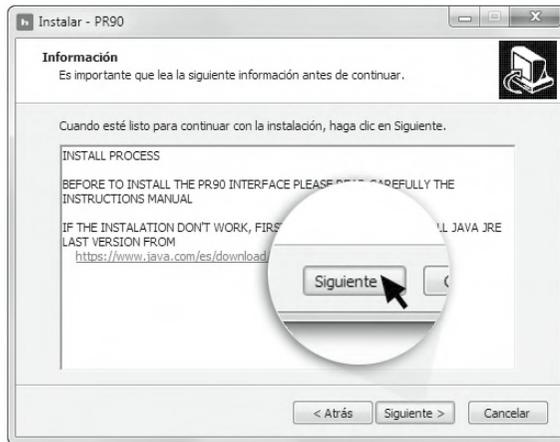


2.2 ... **decompress and run the installation program**

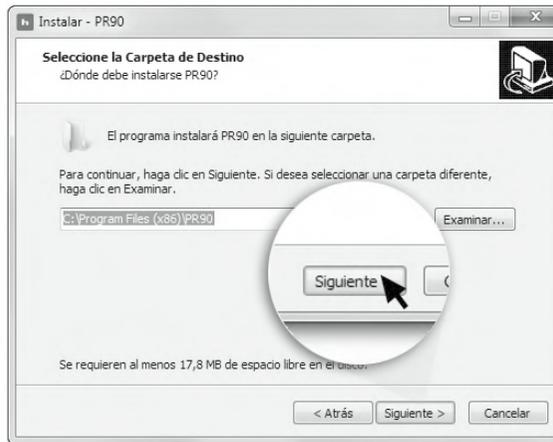
Once the programming software has been downloaded, decompress the .zip file and run the installation program by clicking on the corresponding icon.

- A Choose language and follow the instructions on screen:

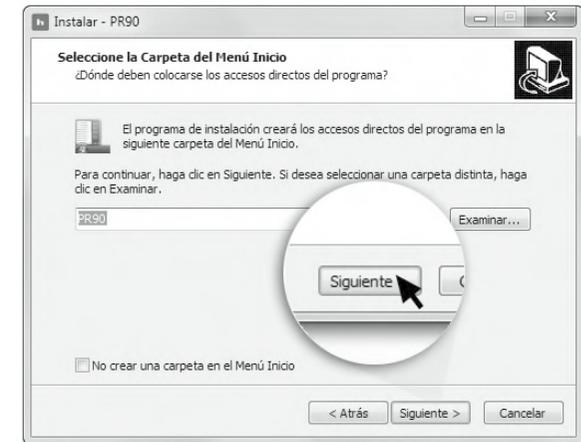




**B** Automatic alert about the installation process



**C** The program will install PR90 - HOHNER in the chosen folder



**D** The installation will create short cuts to the program in the chosen Start Menu folder



**E** Choose the additional tasks; create a desktop icon



**F** The program is ready and configured for installing PR90 on your system



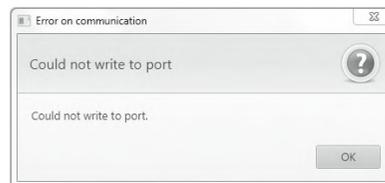
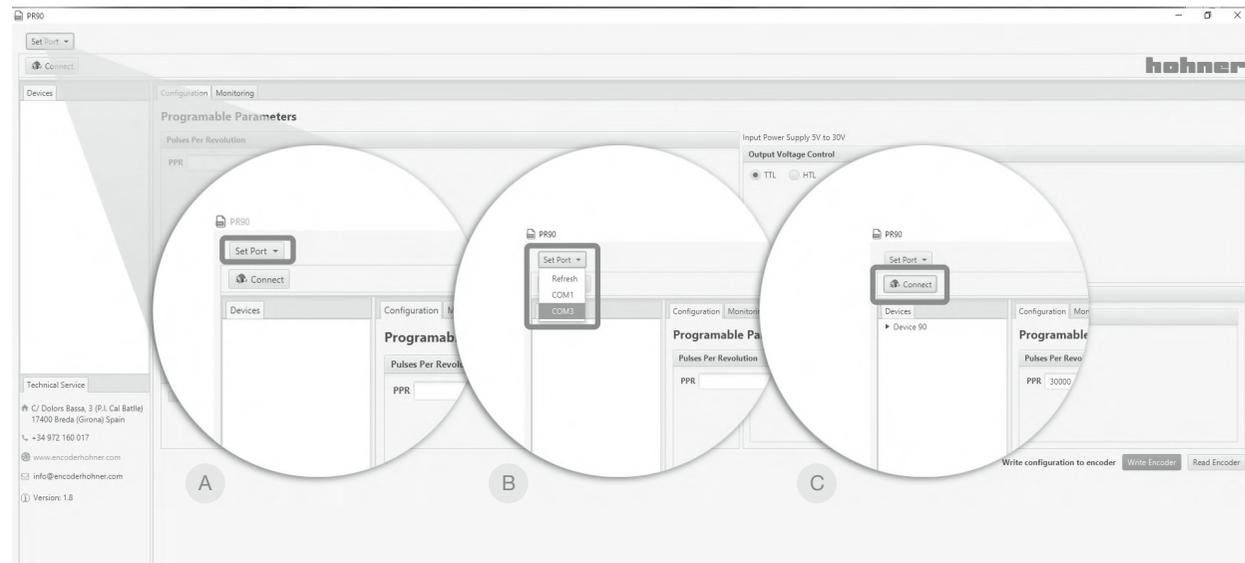
**G** Finish the installation and exit the installation wizard

## Step 3: Run the programming software

3.1 ... **configure the COM port**

Open the **"Set Port"** **A** menu on the interface and choose the corresponding **communications port (COMX)**, **B** where the encoder is connected.

Once chosen, click on the button **Connect** **C** in the upper bar. **C** In approximately 2 seconds the programming interface will fill out with the programming and monitoring screens.



If an error message appears:

1. Close the programming software
2. Disconnect the uUSB/USB cable, and connect it again.
3. Run the programming software, click on "Refresh" and then choose the port where the PR90 is connected **B** from the drop-down menu.



# program





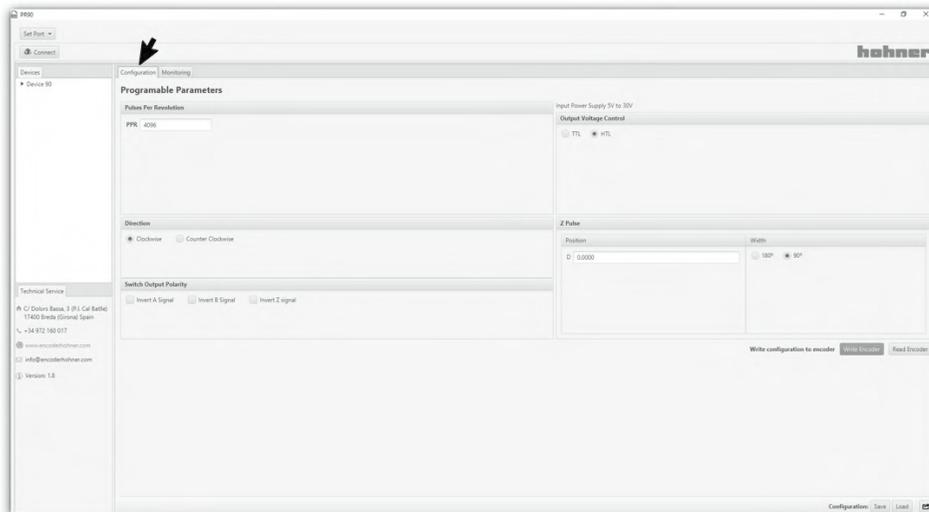
Make sure, before you connect the encoder, that the configuration required for the encoder is the correct type for your application.



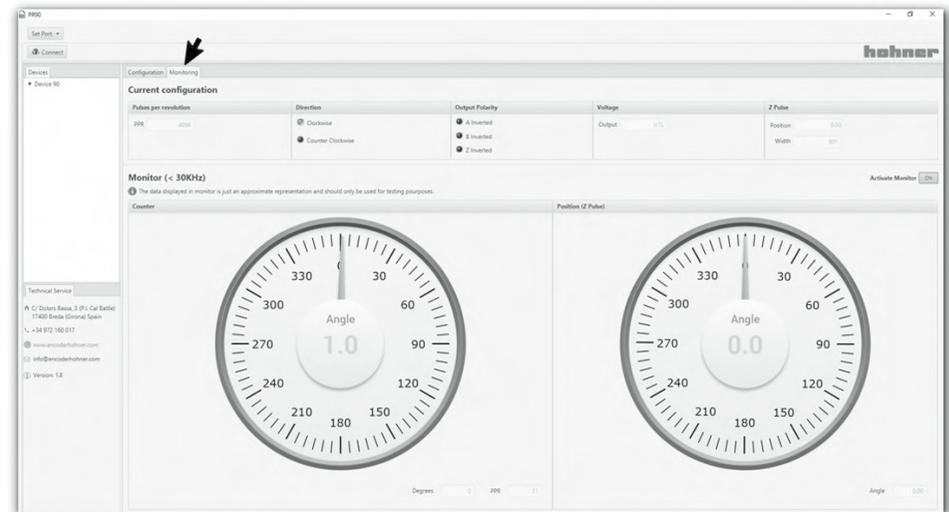
Pay special attention to the TTL / HTL output configuration, since if the proper voltage output is not selected, the devices connected to the encoder could report read errors.

When you connect the device, the computer will recognize the PR90 and you will hear the connecting devices sound and will see a flashing green led on the encoder  for 1 second.

## Programming Screen



## Monitoring Screen



## Programming Screen

The configurable parameters are:

### Pulses per revolution (PPR) from 1 to 65.536 PPR

**A**

**Pulses Per Revolution**

PPR

Enter the desired number of pulses.  
The program detects automatically the PPR value and alerts you with red message "Incorrect PPR" if it is not a valid value.

PPR

PPR

### Output type

**TTL** (RS422 5Vpp. Differential)

**HTL** (Push-Pull 11~30Vpp. Differential)

**B**

Input Power Supply 5V to 30V

**Output Voltage Control**

TTL  HTL

This output can be programmed regardless of input voltage.



*The PR90 encoder considers TTL from 4.5 to 10Vdc and HTL from 11 to 30 Vdc. If input values are below the HTL limit, the PR90 encoder will automatically switch output to TTL.*

### Rotation direction

**C**

**Direction**

Clockwise  Counter Clockwise

**CW** channel A leads B  
(view from the shaft, shaft rotating clockwise)

**CCW** channel B leads A  
(view from the shaft, shaft rotating counterclockwise)

### Switch output polarity

channel by channel  
**A / B / Z**

**D**

**Switch Output Polarity (when required)**

Switch A to nA, nA to A  Switch B to nB, nB to B  Switch Z to nZ, nZ to Z

When required, select one of the output channels to switch the differential output (channel A: from A to nA, nA to A).

### Reference signal width (Index, Z, 0)

**90°** (synchronized with A and B)  
**180°** (synchronized with A)

### Reference signal position (Z)

**E**

**0° to 360°**

**Z Pulse**

Position (when required)

Width  180°  90°

**F**

This setting will move the starting point for electrical connection to the mechanical start point, according to the selected mechanical degrees.

A and B channel synchronization will be maintained at all times.

## Step 4: Program the encoder



*During Power-On programming (encoder powered-up), the PR90 should NEVER be programmed with the machine in operation.*

*At the time of programming information can be lost until programming has finished, and this could cause unexpected behaviour in the machine connected to the encoder.*

4.1

data record

Record configurable parameters selected to the encoder.

**Write Encoder**

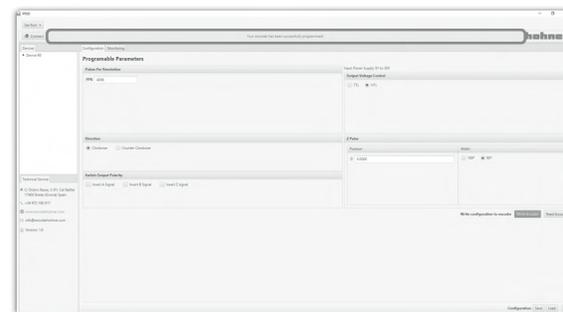
Write configuration to encoder

Write Encoder

Read Encoder

### Record the configuration to the encoder

Once these options have been selected, click on "Write Encoder" in the bottom task-bar of the programming screen. A message window appears, confirming that the recording process has finished correctly.



**Read Encoder**

Write configuration to encoder

Write Encoder

Read Encoder

### Verify the configuration to the encoder

We can verify that the data has been recorded correctly by clicking on "Read Encoder" in the bottom task-bar in the programming screen.



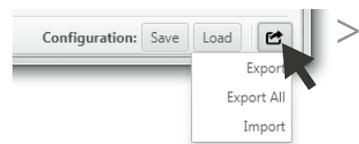
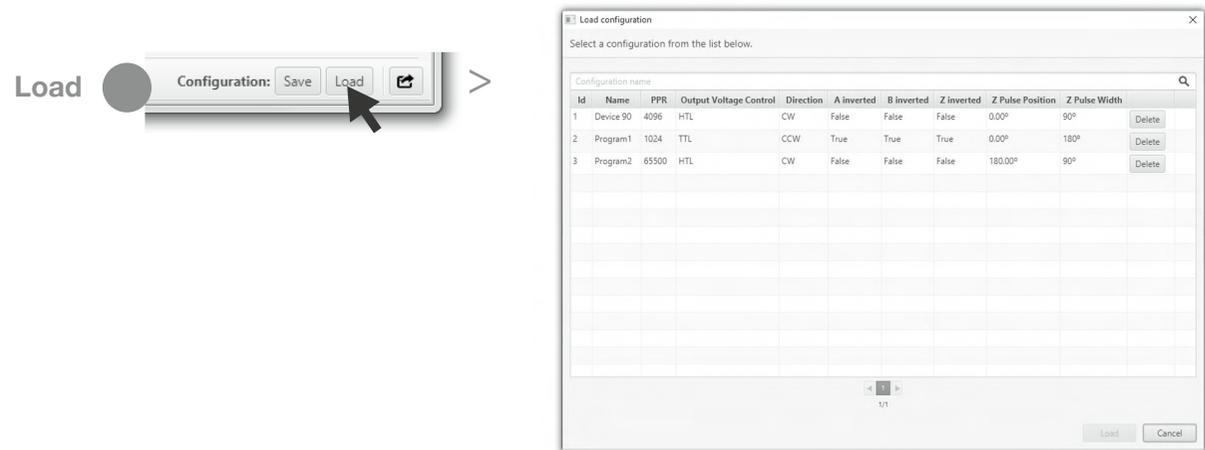
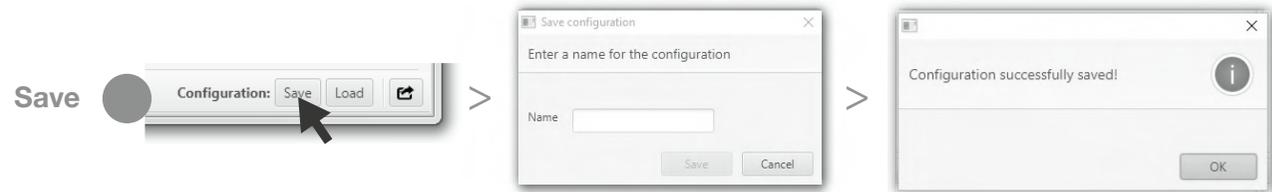
### Default configuration

The encoder comes default preconfigured with:

- Pulses: 4096 ppr
- Output: HTL
- Direction: Clockwise (CW)
- Reference signal position (Z): 0°
- Reference signal width (Index, Z, 0): 90°

4.2 ... **configuration options**  
**Save/Load**

Also you can Save/Load the programming parameters to use them whenever you want without having to repeat the entire selection process. The saved settings are stored in a selectable list and may be loaded as detailed below:



**Export/Import configuration**

- Export encoder configuration in external text document
- Export all saved configurations in external text documents
- Import encoder configuration previously exported

## Monitoring Screen

**Current configuration**

**A**

Pulses per revolution		Direction	Switch Output Polarity (when required)	Voltage	Z Pulse
PPR	<input type="text" value="4096"/>	<input type="radio"/> Clockwise <input checked="" type="radio"/> Counter Clockwise	<input checked="" type="radio"/> Switch A to nA, nA to A <input checked="" type="radio"/> Switch B to nB, nB to B <input checked="" type="radio"/> Switch Z to nZ, nZ to Z	Output <input type="text" value="HTL"/>	Position <input type="text" value="0.0000"/> Width <input type="text" value="90°"/>

### Monitor (< 30KHz)

**i** The data displayed in monitor is just an approximate representation and should only be used for testing purposes.

Activate Monitor



**ON/OFF**

Press the button to activate the read monitor.

**Counter**  
Mechanical (0° to 360°)  
disc position

**B**

Counter	Position (Z Pulse)
<p>Angle <input type="text" value="0.0"/></p> <p>Degrees <input type="text" value="0.0000"/></p>	<p>Angle <input type="text" value="0.0"/></p> <p>Angle <input type="text" value="0.0000"/></p>

**C**

**Reference signal position (Z Pulse)**

Electrical (Z) vs. Mechanical (0° to 360°) reference signal positioning, in numerical and graphical on the dial.



The PR90 encoder can be monitored with frequencies below 30 KHz (30.000 PPS).

## Step 5: Close encoder and labeling

5.1

### close

Once you have configured the encoder, you must close the programming software and disconnect the uUSB/USB cable. Then close the protective cover.



*It is imperative to close the connection cover again to ensure IP65 protection.*

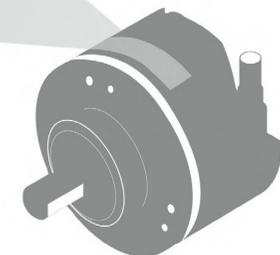


5.2

### labeling

It is recommended that you write the programming data on the encoder's "SETTINGS" label.

<b>SETTINGS</b>	<b>Resolution PPR</b>	<b>Direction</b>	
	<input type="text"/>	<input type="checkbox"/> cw	<input type="checkbox"/> ccw
	<b>Output voltage</b>	<b>Z Pulse</b>	
	<input type="checkbox"/> HTL <input type="checkbox"/> TTL	<input type="checkbox"/> Z 90°	<input type="checkbox"/> Z 180°



## Troubleshooting

	Problem	Cause	Solution
	<b>The PR90/PR90H does not communicate with the PC</b>	Computer needs the installation of USB Drivers	➔ Connect the computer to internet to install USB drivers automatically. Older versions of Windows could need a manual installation of USB drivers. Available at <a href="http://www.encoderhohner.com/pr90">http://www.encoderhohner.com/pr90</a>
		Your computer belongs to a Windows Domain	➔ The Domain Administrator must give to computer user administration rights.
	<b>The communications port is not listed in the programming interface</b>	Unstable cable connection	➔ Reconnect the cable until your OS recognizes it and restart the interface.
		Operating System Collapse	➔ Restart the OS and the PR90 interface.
		uUSB-USB cable is broken	➔ Replace the cable.
	<b>Error "Could not write to port"</b>	Fail connection between the programming software and the encoder	➔ <ol style="list-style-type: none"><li>1. Close the programming software</li><li>2. Disconnect the uUSB/USB cable, and connect it again.</li><li>3. Run the programming software and connect it with the encoder.</li></ol>
	<b>PLC/driver error message</b>	Wrong selection of output type (TTL - HTL) in PR90 programming interface	➔ Review and choose the right programmed output type.

 During Power-Off programming the encoder can show a flashing red led. It doesn't mean a wrong connection or programming error.

## Considerations

### **i** Power Supply

This incremental encoder allows you to work at any voltage from 5 to 30Vdc without the need for any change or adjustment. However, you should pay attention to the polarity of the Vdc connection.

It is recommended in all instances to use a power supply that support loads in excess of 2 Amp., to ensure a very low power impedance and therefore better signal quality and the power supply correct start-up.

### **i** Connectivity

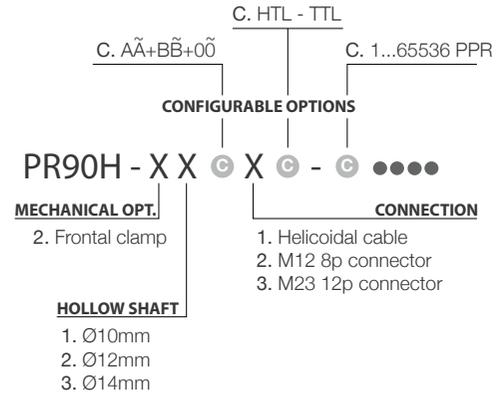
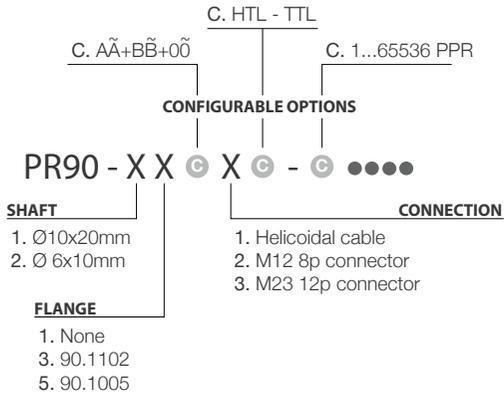
Each differential output channel is identified by the colour of the wires, which plug directly into the differential PLC or Driver inputs. In order to preserve the quality of the signal, this equipment must be mounted on differential resistive loads.

In case of confusion in the connection, this can be corrected without need for disconnection, through the graphical programming interface.

### **i** Differentiated earth line

The equipment is absolutely shielded against external influences, electromagnetic fields and discharges. Even so, it is advisable to establish a differentiated earthing circuit. Branched earthing distribution.

### **i** Reference



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